

ServoMaster: Metadata: controller/transition

1. Definition

`controller/transition` *feature* returns `true` if the hardware is capable of providing the hardware transition control.

Examples are Ohmark Digital Servo Controller and [AdvancedServo](#).

There's a lot of possible transition types, which may or may not be defined later (in particular, *constant velocity* and *constant acceleration*). At this time, this feature is rather for informational purposes.